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KEY=AND - JERAMIAH DARRYL

Materials Handling News

Modeling and Control of Robotic Manipulators and Manufacturing Processes

Presented at the Winter Annual Meeting of the American Society of Mechanical Engineers, Boston, Massachusetts, December 13-18, 1987

IJCNN '93 - Nagoya

Proceedings of 1993 International Joint Conference on Neural Networks, Nagoya Congress Center, October 25-29, 1993, Japan

Supermolecular Science Division Electrotechnical Laboratory

1995 American Control Conference

Institute of Electrical & Electronics Engineers(IEEE)

1986 Proceedings

Proceedings

1986 Proceedings

Human-Robot Interaction

A Survey

Now Publishers Inc *Human-Robot Interaction: A Survey presents a unified treatment of HRI-related issues, identifies key themes, and discusses challenge problems that are likely to shape the field in the near future. The survey includes research results from a cross section of the universities, government efforts, industry labs, and countries that contribute to HRI, and a cross section of the disciplines that contribute to the field, such as human factors, robotics, cognitive psychology and design*

Embedded Robotics

Mobile Robot Design and Applications with Embedded Systems

Springer Science & Business Media *This book presents a unique examination of mobile robots and embedded systems, from introductory to intermediate level. It is structured in three parts, dealing with Embedded Systems (hardware and software design, actuators, sensors, PID control, multitasking), Mobile Robot Design (driving, balancing, walking, and flying robots), and Mobile Robot Applications (mapping, robot soccer, genetic algorithms, neural networks, behavior-based systems, and simulation). The book is written as a text for courses in computer science, computer engineering, IT, electronic engineering, and mechatronics, as well as a guide for robot hobbyists and researchers.*

Automotive Engineering

Parallel Robots

Springer Science & Business Media *Parallel robots are closed-loop mechanisms presenting very good performances in terms of accuracy, velocity, rigidity and ability to manipulate large loads. They have been used in a large number of applications ranging from astronomy to flight simulators and are becoming increasingly popular in the field of machine-tool industry. This book presents a complete synthesis of the latest results on the possible mechanical architectures, analysis and synthesis of this type of mechanism. It is intended to be used by students (with over 150 exercises and numerous internet addresses), researchers (with over 650 references and anonymous ftp access to the code of some algorithms presented in this book) and engineers (for which practical results, mistakes to avoid, and applications are presented). Since the publication of the first edition (2000) there has been an impressive increase in terms of study and use of this kind of structure that are reported in this book. This second edition has been completely overhauled. The initial chapter on kinematics has been split into Inverse Kinematics and Direct Kinematics. A new chapter on calibration was added. The other chapters have also been rewritten to a large extent. The reference section has been updated to include around 45% new works that appeared after the first edition.*

Fundamentals of Robotic Mechanical Systems

Theory, Methods, and Algorithms

Springer *Modern robotics dates from the late 1960s, when progress in the development of microprocessors made possible the computer control of a multiaxial manipulator. Since then, robotics has evolved to connect with many branches of science and engineering, and to encompass such diverse fields as computer vision, artificial intelligence, and speech recognition. This book deals with robots - such as remote manipulators, multifingered hands, walking machines, flight simulators, and machine tools - that rely on mechanical systems to perform their tasks. It aims to establish the foundations on which the design, control and implementation of the underlying mechanical systems are based. The treatment assumes familiarity with some calculus, linear algebra, and elementary mechanics; however, the elements of rigid-body mechanics and of linear transformations are reviewed in the first chapters, making the presentation self-contained. An extensive set of exercises is included. Topics covered include: kinematics and dynamics of serial manipulators with decoupled architectures; trajectory planning; determination of the angular velocity and angular acceleration of a rigid body from point data; inverse and direct kinematics manipulators; dynamics of general parallel manipulators of the platform type; and the kinematics and dynamics of rolling robots. Since the publication of the previous edition there have been numerous advances in both the applications of robotics (including in laprascopy, haptics, manufacturing, and most notably space exploration) as well as in the theoretical aspects (for example, the proof that Husty's 40th-degree polynomial is indeed minimal - mentioned as an open question in the previous edition).*

Direct-Drive Robots

Theory and Practice

Mit Press *An introduction to the design concept and control issues of the high-performance direct-drive robot arm.*

Introduction to AI Robotics, second edition

MIT Press *A comprehensive survey of artificial intelligence algorithms and programming organization for robot systems, combining theoretical rigor and practical applications. This textbook offers a comprehensive survey of artificial intelligence (AI) algorithms and programming organization for robot systems. Readers who master the topics covered will be able to design and evaluate an artificially intelligent robot for applications involving sensing, acting, planning, and learning. A background in AI is not required; the book introduces key AI topics from all AI subdisciplines throughout the book and explains how they contribute to autonomous capabilities. This second edition is a major expansion and reorganization of the first edition, reflecting the dramatic advances made in AI over the past fifteen years. An introductory overview provides a framework for thinking about AI for robotics, distinguishing between the fundamentally different design paradigms of automation and autonomy. The book then discusses the reactive functionality of sensing and acting in AI robotics; introduces the deliberative functions most often associated with intelligence and the capability of autonomous initiative; surveys multi-robot systems and (in a new chapter) human-robot interaction; and offers a "metaview" of how to design and evaluate autonomous systems and the ethical considerations in doing so. New material covers locomotion, simultaneous localization and mapping, human-robot interaction, machine learning, and ethics. Each chapter includes exercises, and many chapters provide case studies. Endnotes point to additional reading, highlight advanced topics, and offer robot trivia.*

Robust Control Design with MATLAB®

Springer Science & Business Media *Shows readers how to exploit the capabilities of the MATLAB® Robust Control and Control Systems Toolboxes to the fullest using practical robust control examples.*

Bipedal Robots

Modeling, Design and Walking Synthesis

John Wiley & Sons *This book presents various techniques to carry out the gait modeling, the gait patterns synthesis, and the control of biped robots. Some general information on the human walking, a presentation of the current experimental biped robots, and the application of walking bipeds are given. The modeling is based on the decomposition on a walking step into different sub-phases depending on the way each foot stands into contact on the ground. The robot design is dealt with according to the mass repartition and the choice of the actuators. Different ways to generate walking patterns are considered, such as passive walking and gait synthesis performed using optimization technique. Control based on the robot modeling, neural network methods, or intuitive approaches are presented. The unilaterality of contact is dealt with using on-line adaptation of the desired motion.*

RoboCup 2002: Robot Soccer World Cup VI

Springer *RoboCup 2002, the 6th Robot World Cup Soccer and Rescue Competitions and Conference, took place during June 19–25, 2002, at the Fukuoka Dome (main venue) in Fukuoka, Japan. It was, by far, the RoboCup event with the largestnumberofregisteredparticipants(1004persons,distributedin188teams from 29 countries) and visitors (around 120,000 persons). As was done in its previous editions since 1997, the event included several robotic competitions and aninternationalsymposium.Thepapersandposterspresentedatthesymposium constitutethemainpartofthisbook.Leaguereportsinthe?nalsectiondescribe signi?cant advances in each league and the results. The symposium organizers received 76 submissions, among which 17 papers (22%) were accepted for oral presentation at the symposium (?rst section of the book), and 21 papers (29%) were accepted as posters (second section of the book). Most papers were evaluated by three reviewers each, chosen from the members of the International Program Committee (IPC). The IPC consisted of a balanced combination of regular RoboCup participants and researchers from outside this community. The reviewers worked hard to guarantee a fair review process – the result of their work was a high-quality symposium with very - teresting presentations.*

Computational Support for Sketching in Design

A Review

Now Publishers Inc *Computational Support for Sketching in Design surveys the literature on sketch based tools from journals, conference proceedings, symposia and workshops in human-computer interaction, cognitive science, design research, computer science, artificial intelligence, and engineering design.*

Control Problems in Robotics and Automation

Springer *Focusing on the important control problems in state-of-the-art robotics and automation, this volume features invited papers from a workshop held at CDC, San Diego, California. As well as looking at current problems, it aims to identify and discuss challenging issues that are yet to be solved but which will be vital to future research directions. The many topics covered include: automatic control, distributed multi-agent control, multirobots, dexterous hands, flexible manipulators, walking robots, free-floating systems, nonholonomic robots, sensor fusion, fuzzy control, virtual reality, visual servoing, and task synchronization. Control Problems in Robotics and Automation will be of interest to all researchers, scientists and graduate students who wish to broaden their knowledge in robotics and automation and prepare themselves to address and resolve the control problems that will be faced in this field as we enter the twenty-first century.*

Fundamentals Of Robotics: Linking Perception To Action

World Scientific Publishing Company *Tomorrow's robots, which includes the humanoid robot, can perform task like tutoring children, working as tour guides, driving humans to and from work, do the family shopping etc. Tomorrow's robots will enhance lives in ways we never dreamed possible. No time to attend the decisive meeting on Asian strategy? Let your robot go for you and make the decisions. Not feeling well enough to go to the clinic? Let Dr Robot come to you, make a diagnosis, and get you the necessary medicine for treatment. No time to coach the soccer team this week? Let the robot do it for you.Tomorrow's robots will be the most exciting and revolutionary things to happen to the world since the invention of the automobile. It will change the way we work, play, think, and live. Because of this, nowadays robotics is one of the most dynamic fields of scientific research. These days, robotics is offered in almost every university in the world. Most mechanical engineering departments offer a similar course at both the undergraduate and graduate levels. And increasingly, many computer and electrical engineering departments are also offering it.This book will guide you, the curious beginner, from yesterday to tomorrow. The book will cover practical knowledge in understanding, developing, and using robots as versatile equipment to automate a variety of industrial processes or tasks. But, the book will also discuss the possibilities we can look forward to when we are capable of creating a vision-guided, learning machine.*

Proceedings of the IEEE International Conference on Industrial Technology

Principles of Robot Motion

Theory, Algorithms, and Implementations

MIT Press *A text that makes the mathematical underpinnings of robot motion accessible and relates low-level details of implementation to high-level algorithmic concepts. Robot motion planning has become a major focus of robotics. Research findings can be applied not only to robotics but to planning routes on circuit boards, directing digital actors in computer graphics, robot-assisted surgery and medicine, and in novel areas such as drug design and protein folding. This text reflects the great advances that have taken place in the last ten years, including sensor-based planning, probabalistic planning, localization and mapping, and motion planning for dynamic and nonholonomic systems. Its presentation makes the mathematical underpinnings of robot motion accessible to students of computer science and engineering, rleating low-level implementation details to high-level algorithmic concepts.*

Electromagnetic Actuation and Sensing in Medical Robotics

Springer *This book highlights electromagnetic actuation (EMA) and sensing systems for a broad range of applications including targeted drug delivery, drug-release-rate control, catheterization, intravitreal needleless injections, wireless magnetic capsule endoscopy, and micromanipulations. It also reviews the state-of-the-art magnetic actuation and sensing technologies with remotely controlled targets used in biomedicine.*

Biomimetic and Biohybrid Systems

Second International Conference, Living Machines 2013, London, UK, July 29 -- August 2, 2013, Proceedings

Springer *This book constitutes the refereed proceedings of the second International Conference on Biomimetic and Biohybrid Systems, Living Machines 2013, held in London, UK, in July/August 2013. The 65 revised full papers presented were carefully reviewed and selected from various submissions. The papers are targeted at the intersection of research on novel live-like technologies inspired by scientific investigation of biological systems, biomimetics, and research that seeks to interface biological and artificial systems to create biohybrid systems*

Health Monitoring of Aerospace Structures

Smart Sensor Technologies and Signal Processing

John Wiley & Sons *Providing quality research for the reader, this title encompasses all the recent developments in smart sensor technology for health monitoring in aerospace structures, providing a valuable introduction to damage detection techniques. Focussing on engineering applications, all chapters are written by smart structures and materials experts from aerospace manufacturers and research/academic institutions. This key reference: Discusses the most important aspects related to smart technologies for damage detection; this includes not only monitoring techniques but also aspects related to specifications, design parameters, assessment and qualification routes. Presents real case studies and applications; this includes in-flight tests; the work presented goes far beyond academic research applications. Displays a balance between theoretical developments and engineering applications*

Moon

Prospective Energy and Material Resources

Springer Science & Business Media *The Earth has limited material and energy resources. Further development of the humanity will require going beyond our planet for mining and use of extraterrestrial mineral resources and search of power sources. The exploitation of the natural resources of the Moon is a first natural step on this direction. Lunar materials may contribute to the betterment of conditions of people on Earth but they also may be used to establish permanent settlements on the Moon. This will allow developing new technologies, systems and flight operation techniques to continue space exploration. In fact, a new branch of human civilization could be established permanently on Moon in the next century. But, meantime, an inventory and proper social assessment of Moon's prospective energy and material resources is required. This book investigates the possibilities and limitations of various systems supplying manned bases on Moon with energy and other vital resources. The book collects together recent proposals and innovative options and solutions. It is a useful source of condensed information for specialists involved in current and impending Moon-related activities and a good starting point for young researchers.*

Intelligent Energy Field Manufacturing

Interdisciplinary Process Innovations

CRC Press *Edited by prominent researchers and with contributions from experts in their individual areas, Intelligent Energy Field Manufacturing: Interdisciplinary Process Innovations explores a new philosophy of engineering. An in-depth introduction to Intelligent Energy Field Manufacturing (EFM), this book explores a fresh engineering methodology that not only integrates but goes beyond methodologies such as Design for Six Sigma, Lean Manufacturing, Concurrent Engineering, TRIZ, green and sustainable manufacturing, and more. This book gives a systematic introduction to classic non-mechanical manufacturing processes as well as offering big pictures of some technical frontiers in modern engineering. The book suggests that any manufacturing process is actually a process of injecting human intelligence into the interaction between material and the various energy fields in order to transfer the material into desired configurations. It discusses technological innovation, dynamic M-PIE flows, the generalities of energy fields, logic functional materials and intelligence, the open scheme of intelligent EFM implementation, and the principles of intelligent EFM. The book takes a highly interdisciplinary approach that includes research frontiers such as micro/nano fabrication, high strain rate processes, laser shock forming, materials science and engineering, bioengineering, etc., in addition to a detailed treatment of the so called "non-traditional" manufacturing processes, which covers waterjet machining, laser material processing, ultrasonic material processing, EDM/ECM, etc. Filled with illustrative pictures, figures, and tables that make technical materials more absorbable, the book cuts across multiple engineering disciplines. The majority of books in this area report the facts of proven knowledge, while the behind-the-scenes thinking is usually neglected. This book examines the big picture of manufacturing in depth before diving into the details of an individual process, demonstrating how innovations are achieved. It lowers barriers to technical innovation, meets new engineering challenges, and systematically introduces manufacturing processes.*

21st Century Sports

How Technologies Will Change Sports in the Digital Age

Springer Nature *This book outlines the effects that technology-induced change will have on sport within the next five to ten years, and provides food for thought concerning what lies further ahead. Presented as a collection of essays, the authors are leading academics from renowned institutions such as Massachusetts Institute of Technology, Queensland University of Technology, and the University of Cambridge, and practitioners with extensive technological expertise. In their essays, the authors examine the impacts of emerging technologies like artificial intelligence, the Internet of Things, and robotics on sports and assess how they will change sport itself, consumer behavior, and existing business models. The book will help athletes, entrepreneurs, and innovators working in the sports industry to spot trendsetting technologies, gain deeper insights into how they will affect their activities, and identify the most effective responses to stay ahead of the competition both on and off the pitch.*

Artificial Cognitive Systems

A Primer

MIT Press *A concise introduction to a complex field, bringing together recent work in cognitive science and cognitive robotics to offer a solid grounding on key issues. This book offers a concise and accessible introduction to the emerging field of artificial cognitive systems. Cognition, both natural and artificial, is about anticipating the need for action and developing the capacity to predict the outcome of those actions. Drawing on artificial intelligence, developmental psychology, and cognitive neuroscience, the field of artificial cognitive systems has as its ultimate goal the creation of computer-based systems that can interact with humans and serve society in a variety of ways. This primer brings together recent work in cognitive science and cognitive robotics to offer readers a solid grounding on key issues. The book first develops a working definition of cognitive systems—broad enough to encompass multiple views of the subject and deep enough to help in the formulation of theories and models. It surveys the cognitivist, emergent, and hybrid paradigms of cognitive science and discusses cognitive architectures derived from them. It then turns to the key issues, with chapters devoted to autonomy, embodiment, learning and development, memory and prospection, knowledge and representation, and social cognition. Ideas are introduced in an intuitive, natural order, with an emphasis on the relationships among ideas and building to an overview of the field. The main text is straightforward and succinct; sidenotes drill deeper on specific topics and provide contextual links to further reading.*

RITA 2018

Proceedings of the 6th International Conference on Robot Intelligence Technology and Applications

Springer *This book gathers the Proceedings of the 6th International Conference on Robot Intelligence Technology and Applications (RITA 2018). Reflecting the conference's main theme, "Robotics and Machine Intelligence: Building Blocks for Industry 4.0," it features relevant and current research investigations into various aspects of these building blocks. The areas covered include: Instrumentation and Control, Automation, Autonomous Systems, Biomechatronics and Rehabilitation Engineering, Intelligent Systems, Machine Learning, Robotics, Sensors and Actuators, and Machine Vision, as well as Signal and Image Processing. A valuable asset, the book offers researchers and practitioners a timely overview of the latest advances in robot intelligence technology and its applications.*

Distributed Autonomous Robotic Systems 7

Springer Science & Business Media This book collects papers selected by an international program committee for presentation at the 8th International Symposium on Distributed Autonomous Robotic Systems. The papers present state of the art research advances in the field of distributed robotics. What makes this book distinctive is the emphasis on using multiple robots and on making them autonomous, as opposed to being teleoperated. Novel algorithms, system architectures, technologies, and numerous applications are covered.

Intelligent Systems and Applications

Extended and Selected Results from the SAI Intelligent Systems Conference (IntelliSys) 2015

Springer This book is a remarkable collection of chapters covering a wider range of topics, including unsupervised text mining, anomaly and Intrusion Detection, Self-reconfiguring Robotics, application of Fuzzy Logic to development aid, Design and Optimization, Context-Aware Reasoning, DNA Sequence Assembly and Multilayer Perceptron Networks. The twenty-one chapters present extended results from the SAI Intelligent Systems Conference (IntelliSys) 2015 and have been selected based on high recommendations during IntelliSys 2015 review process. This book presents innovative research and development carried out presently in fields of knowledge representation and reasoning, machine learning, and particularly in intelligent systems in a more broad sense. It provides state - of - the - art intelligent methods and techniques for solving real world problems along with a vision of the future research.

Electronic Portable Instruments

Design and Applications

CRC Press With the availability of advanced technologies, digital systems, and communications, portable instruments are rapidly evolving from simple, stand alone, low-accuracy measuring instruments to complex multifunctional, network integrated, high-performance digital devices with advanced interface capabilities. The relatively brief treatments these instruments receive in many books are no longer adequate. Designers, engineers and scientists need a comprehensive reference dedicated to electronic portable instruments that explains the state-of-art and future directions. Electronic Portable Instruments: Design and Applications introduces the basic measurement and instrumentation concepts, describes the operating principles, and discusses the typical specifications of three main groups of portable instruments: Portable and handheld instruments built for specific applications Intelligent sensor-based devices with few components and dedicated features, such as implantable medical devices Portable data systems containing fixed sensors and supporting mechanisms, but equipped with advanced communications capabilities, such as mobile weather stations The author discusses sensors suitable for these instruments, addresses how components are selected, and clearly shows that instrument design centers on trade-offs between costs, performance, size and weight, power consumption, interface options, ruggedness, and the ability to operate in a range of environments. A multitude of tables, formulae, and figures--many in full color--enhance the presentation. Numerous examples of applications demonstrate the current diversity of these devices and point the way to future trends in development and applications.

Microbial Production

From Genome Design to Cell Engineering

Springer Science & Business Media Microbial production: From genome design to cell surface engineering affords a comprehensive review of novel technology and approaches being implemented for manufacturing microorganisms, written by specialists in both academia and industry. This book is divided into three sections: the first includes technology for improvement of fermentation strains and many supporting technologies and information; the second examines novel technology useful for analysis of cell activities, analyzing gene function, and designing genomes of producer strains; and finally, a discussion of the practical application of the techniques and success case studies in many fields of bio-production, such as microbiological production, pharmaceuticals, chemicals, foods and cosmetics.

Control Problems in Robotics

Springer Science & Business Media The ?eld of robotics continues to ?ourish and develop. In common with general scienti?c investigation, new ideas and implementations emerge quite spontaneously and these are discussed, used, discarded or subsumed at c- ferences, in the reference journals, as well as through the Internet. After a little more maturity has been acquired by the new concepts, then archival publication as a scienti?c or engineering monograph may occur. The goal of the Springer Tracts in Advanced Robotics is to publish new developments and advances in the ?elds of robotics research – rapidly and informally but with a high quality. It is hoped that prospective authors will welcome the opportunity to publish a structured presentation of some of the emerging robotics methodologies and technologies. The edited volume by Antonio Bicchi, Henrik Christensen and Domenico Prattichizzo is the outcome of the second edition of a workshop jointly sponsored by the IEEE Control Systems Society and the IEEE Robotics and Automation Society. Noticeably, the previous volume was published in the Springer Lecture Notes on Control and Information Sciences. The authors are recognised as leading scholars internationally. A n- ber of challenging control problems on the forefront of today's research in robotics and automation are covered, with special emphasis on vision, sensory-feedback control, human-centered robotics, manipulation, planning, ?exible and cooperative robots, assembly systems.

GIS-based Studies in the Humanities and Social Sciences

CRC Press Studies in the humanities and the social sciences can be enhanced through the use of geographic information systems (GIS). However, this computer-aided method of analysis is worthless unless researchers can devote the time necessary to learn what it is, what it can do, and how to use it. Resulting from a six-year project entitled Spatial Information Science for the Humanities and Social Sciences (SIS for HSS), GIS-Based Studies in the Humanities and Social Sciences details the tools and processes for deploying GIS in economic and social analyses. Through the use of this book, readers can understand how GIS technology can be utilized in advancing studies. This volume will also encourage professionals in humanities and the social sciences to employ new GIS-based methods in their own research.

JSME International Journal

Dynamics, control, robotics, design and manufacturing. Series C

Dynamics of Manipulation Robots

Theory and Application

Springer Science & Business Media *This monograph represents the first book of the series entitled "SCI ENTIFIC FUNDAMENTALS OF ROBOTICS". The aim of this monograph is to ap proach the dynamics of active mechanisms from the standpoint of its application to the synthesis of complex motion and computer-aided de sign of manipulation mechanisms with some optimal performances. The rapid development of a new class of mechanisms, which may be referred to as active mechanisms, contributed to their application in various environments (from underwater to cosmic) . Because of some specific fea tures, these mechanisms require very careful description, both in a mechanical sense (kinematic and dynamic) and in the synthesis of algo rithms for precise tracking of the above motion under insufficiently defined operating conditions. Having also in mind the need for a very fast (even real-time) calculation of system dynamics and for eliminating, in principle, the errors made when forming mathematical models "by hand" this monograph will primarily present methods for automatic for mUlation of dynamic equations of motion of active spatial mechanisms. Apart from these computer-oriented methods, mention will be made of all those methods which have preceded the computer-oriented procedures, predominantly developed for different problems of rigid body dynamics. If we wish to systematically establish the origins of the scientific discipline, which could be called robot dynamics, we must recall some groups and individuals, who, by solving actual problems in the synthe sis and control of artificial motion, have contributed to a gradual formation of this discipline.*

Wireless Sensors and Instruments

Networks, Design, and Applications

CRC Press *Advances such as 3-G mobile communications networks demonstrate the increasing capability of high-quality data transmission over wireless media. Adapting wireless functionality into instrument and sensor systems endows them with unmatched flexibility, robustness, and intelligence. Wireless Sensors and Instruments: Networks, Design, and Applications explains the principles, state-of-the-art technologies, and modern applications of this burgeoning field. From underlying concepts to practical applications, this book outlines all the necessary information to plan, design, and implement wireless instrumentation and sensor networks effectively and efficiently. The author covers the basics of instruments, measurement, sensor technology, communication systems, and networks along with the theory, methods, and components involved in digital and wireless instruments. Placing these technologies in context, the book also examines the principles, components, and techniques of modern communication systems followed by network standards, protocols, topologies, and security. Building on these discussions, the book uses examples to illustrate the practical aspects of constructing sensors and instruments. Finally, the author devotes the closing chapter to applications in a broad array of fields, including commercial, human health, and consumer products applications. Filled with up-to-date information and thorough coverage of fundamentals, Wireless Sensors and Instruments: Networks, Design, and Applications supplies critical, hands-on tools for efficiently, effectively, and immediately implementing advanced wireless systems.*

An Introduction to 3D Computer Vision Techniques and Algorithms

John Wiley & Sons *Computer vision encompasses the construction of integrated vision systems and the application of vision to problems of real-world importance. The process of creating 3D models is still rather difficult, requiring mechanical measurement of the camera positions or manual alignment of partial 3D views of a scene. However using algorithms, it is possible to take a collection of stereo-pair images of a scene and then automatically produce a photo-realistic, geometrically accurate digital 3D model. This book provides a comprehensive introduction to the methods, theories and algorithms of 3D computer vision. Almost every theoretical issue is underpinned with practical implementation or a working algorithm using pseudo-code and complete code written in C++ and MatLab®. There is the additional clarification of an accompanying website with downloadable software, case studies and exercises. Organised in three parts, Cyganek and Siebert give a brief history of vision research, and subsequently: present basic low-level image processing operations for image matching, including a separate chapter on image matching algorithms; explain scale-space vision, as well as space reconstruction and multiview integration; demonstrate a variety of practical applications for 3D surface imaging and analysis; provide concise appendices on topics such as the basics of projective geometry and tensor calculus for image processing, distortion and noise in images plus image warping procedures. An Introduction to 3D Computer Vision Algorithms and Techniques is a valuable reference for practitioners and programmers working in 3D computer vision, image processing and analysis as well as computer visualisation. It would also be of interest to advanced students and researchers in the fields of engineering, computer science, clinical photography, robotics, graphics and mathematics.*